



## Programme Specification

### Robotics {Joint Award}[Frenchay]

Version: 2025-26, v2.0, Validated

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## **Section 1: Key Programme Details**

### **Part A: Programme Information**

**Programme title:** Robotics {Joint Award}[Frenchay]

**Highest award:** MSc Robotics

**Awarding institution:** University of Bristol

**Affiliated institutions:** UWE Bristol

**Teaching institutions:** University of Bristol, UWE Bristol

**Study abroad:** No

**Year abroad:** No

**Sandwich year:** No

**Credit recognition:** No

**School responsible for the programme:** CATE School of Engineering, College of Arts, Technology and Environment

**Professional, statutory or regulatory bodies:** Not applicable

**Modes of delivery:** Full-time

**Entry requirements:** For the current entry requirements see the UWE public website.

**For implementation from:** 01 September 2018

**Programme code:** H67B12

## **Section 2: Programme Overview, Aims and Learning Outcomes**

### **Part A: Programme Overview, Aims and Learning Outcomes**

**Overview:** The MSc Robotics is available through a partnership between UWE Bristol and the University of Bristol, and provides a comprehensive understanding of advanced robotics and automation systems. While providing an excellent background for a range of technology careers that require robotics and automation knowledge and skills, it also offers the specialisms to support doctorate-level studies and ongoing research careers.

### **Features of the programme:**

**Educational Aims:** This MSc aims to provide the background and focus to prepare students to understand, design and implement robotic systems as well as comprehend the foundational methods and relevant theories. The structure allows students from a variety of backgrounds in Engineering, Mathematics, Physics and related disciplines to acquire the skills to become Robotics practitioners and researchers.

The programme is designed to expose students to three fundamental themes: Perception, Action and Cognition. We also promote a hands-on approach to develop intelligent actuating and sensing systems with the final dissertation based at the Bristol Robotics Laboratory, the most comprehensive Robotics Lab in the United Kingdom.

### **Programme Learning Outcomes:**

On successful completion of this programme graduates will achieve the following learning outcomes.

#### **Knowledge and Understanding**

- A1. The ability to understand design and implement robotic systems that link Action, Perception and Cognition.
- A2. Under the theme Action: the modelling and implementation of control strategies for multi-degree of freedom systems and their operation in space and in the proximity of human operators or collaborators.
- A3. Under the theme Perception: the algorithmic and operational principles of perception in time-critical systems with an emphasis on robot vision.

- A4. Under the theme Cognition: the foundational aspects of uncertainty modelling, decision making and learning in artificial and natural systems.
- A5. The integration of a wide variety of methods to include 3D animation principles, navigation, localisation, DSP design and robot programming.
- A6. The acquisition of skills to write, evaluate and conduct research in Robotics.
- A7. The implementation of a real robotic system that combines Action, Perception and Cognition.

### **Intellectual Skills**

- B1. Ability to understand a complex robotic system.
- B2. Capability to identify the requirements and specifications of tasks which are appropriate to be solved using an acting and perceiving intelligent system.
- B3. Critically evaluate robotic systems and designs.
- B4. Conduct research in the area of Robotics.
- B5. Identify the relevant literature and sources to accomplish the above.

### **Transferable Skills and other attributes**

- D1. Work effectively as part of a team demonstrating time management, team coordination and or leadership.
- D2. Access state of the art literature resources in Robotics and related areas.
- D3. Structure and communicate ideas effectively in writing and orally.
- D4. Plan and design projects in several stages.

**Assessment strategy:** The learning outcomes are assessed in the specific units using a range of methods to include coursework which is both practical and theoretical, essays, exams and presentations.

A final dissertation will be expected as part of the project unit which will likely include a presentation to markers. This dissertation is the programme's principal system integration point where students will demonstrate the skills learned throughout the

course. In particular students will demonstrate the ability to design, analyse, implement and evaluate a robotic system under the supervision of BRL academic staff and potentially in collaboration with industry partners. This project is likely to coalesce aspects from the three main strands of the course to include aspects of perception, action and decision making in a working system and guided by the design and integration principles that the students have been exposed to. Further skills such as delivery of results under time constraints and scientific and technical writing will be also demonstrated through the writing of the dissertation.

**Student support:** Teaching for this programme is delivered at both the University of Bristol and the University of the West of England campuses. Students attending the programme will be given free transport passes to travel between the two universities.

## Part B: Programme Structure

### Year 1

#### Year 1 Compulsory Modules - UWE

The student must take 30 credits from Compulsory modules - UWE

| Module Code | Module Title                 | Credit |
|-------------|------------------------------|--------|
| UFMFRR-15-M | Machine Vision 2025-26       | 15     |
| UFMF4X-15-M | Robotic Fundamentals 2025-26 | 15     |

#### Year 1 Optional Modules - UWE

The student must take 30 credits from Optional Modules - UWE

| Module Code | Module Title                          | Credit |
|-------------|---------------------------------------|--------|
| UFMFHP-15-M | Human-Robot Interaction 2025-26       | 15     |
| UFME7F-15-M | Advanced Control and Dynamics 2025-26 | 15     |
| UFMFSR-15-M | Assistive Robotics 2025-26            | 15     |

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|-------------|------------------------------------|----|
| UFME7R-15-M | Robot Learning for Control 2025-26 | 15 |
|-------------|------------------------------------|----|

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**Part C: Higher Education Achievement Record (HEAR) Synopsis****Part D: External Reference Points and Benchmarks****Part E: Regulations**

Approved to University of Bristol Regulations and Procedures