

## **MODULE SPECIFICATION**

Part 1: Information						
Module Title	Robotics Research Training Workshops					
Module Code	UFMF8Y-15-M		Level	Level 7		
For implementation from	2020-	-21				
UWE Credit Rating	15		ECTS Credit Rating	7.5		
Faculty		ty of Environment & nology	Field			
Department	FET Dept of Engin Design & Mathematics					
Module Type:	Stand	lard				
Pre-requisites		None				
Excluded Combinations		None				
Co-requisites		None				
Module Entry Requirements		None				
PSRB Requirements		None				

# Part 2: Description

**Overview**: This module complements the research development 'soft skills' covered in the University of Bristol led Robotics Research Preparation unit

**Educational Aims:** The Robotics Research Training module provides the students with handson introductory training on skills needed for research in robotics. The knowledge is delivered in a hands-on style through half-day and day workshops by academics and guest speakers from industry.

**Outline Syllabus:** The topics that will be covered in the workshops are of a wide range. They have been chosen to cover many different needed skills that are needed by a successful robotics researcher. Example for the topics that will be covered are as follows:

Fundamental mathematical methods for solving robotics problems.

Introduction to Robot Operating System (ROS).

Programming robots in C++ and Python.

Introduction to project management and managing your own research.

Usage of computer-aided design and rapid prototyping techniques to manufacture robot components.

## STUDENT AND ACADEMIC SERVICES

Principles of responsible innovation and their importance in robotics and autonomous systems. Introduction to electronics components for robotics.

**Teaching and Learning Methods:** The module will make use of existing facilities provided at the Bristol Robotics Laboratory and guest lectures provided by industry partners. The module will be delivered by the CDT Management team, the CDT technician and guest lecturers. Specialist facilities at BRL will be employed including rapid prototyping and small-group Linux computer teaching room.

The module will be structured in 12 x 1-day training sessions organised as workshops on relevant topics (72 hours). Reading and self-study preparatory assignments (e.g. online programming tutorials or homework problem sheets) will be set in advance, totalling approx. 4 hours per workshop (48 hours). Online reflective account assignment sized to require 12 hours total.

#### Part 3: Assessment

The module will be assessed in two components.

Component A will assess the participation in the workshops and will be assessed by in-workshop exercises. The students will be asked to individually present the workshop results of at least 9 of the 12 workshops in a portfolio.

Component B will require individual reflective accounts of the training experience, including a critical review of the tools encountered and frameworks introduced, assessed through a structured set of online questions demanding text responses. Students have to answer at least 9 of the 12 workshop questionnaires.

#### Resit Strategy

Component A will require the submission of an individually prepared report containing a critical discussion of 9 of the workshop topics.

Component B will require students to answer at least 9 of the 12 online workshop questionnaires.

First Sit Components	Final Assessment	Element weighting	Description
Portfolio - Component A	✓	75 %	A portfolio of workshop exercises.
In-class test - Component B		25 %	Questionnaires
Resit Components	Final Assessment	Element weighting	Description
Report - Component A		75 %	Report (up to 3000 words).
In-class test - Component B		25 %	Questionnaires

	Part 4: Teaching and Learning Methods	
Learning Outcomes	On successful completion of this module students will achieve the following learning	outcomes:
	Module Learning Outcomes	Reference
	Solve robotics problems using mathematical models, e.g. design and interpretation of experiments using statistics and analysis of kinematics and reference frames using linear algebra	MO1
	Solve computer programming challenges using appropriate tools, including the Robotics Operating System (ROS) and good structure and style in Python or C++	MO2

# STUDENT AND ACADEMIC SERVICES

	Manufacture simple robot components by applying computer-aided de rapid prototyping techniques	esign and	MO3			
	Appraise principles of Responsible Innovation (RI) on given examples from robotics research by using the ethics frameworks as for example the AREA framework					
	Critically discuss the importance of Responsible Innovation Robotics Autonomous Systems and apply RI methods to their own research	s and	MO5			
	Effectively apply project management approaches to plan their own reprojects	MO6				
Contact Hours	Independent Study Hours:					
	Independent study/self-guided study	4	8			
	Total Independent Study Hours:	8				
	Scheduled Learning and Teaching Hours:					
	Face-to-face learning	7	2			
	Total Scheduled Learning and Teaching Hours:	7	2			
	Hours to be allocated		150			
	Allocated Hours	12	120			
Reading List	The reading list for this module can be accessed via the following link:		_			
	https://rl.talis.com/3/uwe/lists/03E4CF79-1C3E-592D-335C-1A97BD15	F28E.html				

	Part 5: Contributes Towards
This	s module contributes towards the following programmes of study: