



Module Specification

Fundamental Robotics Principles

Version: 2023-24, v5.0, 22 Sep 2023

Contents

Module Specification	1
Part 1: Information	2
Part 2: Description	2
Part 3: Teaching and learning methods	3
Part 4: Assessment.....	4
Part 5: Contributes towards	6

Part 1: Information

Module title: Fundamental Robotics Principles

Module code: UFMFKT-30-1

Level: Level 4

For implementation from: 2023-24

UWE credit rating: 30

ECTS credit rating: 15

College: College of Arts, Technology and Environment

School: CATE School of Engineering

Partner institutions: None

Field: Engineering, Design and Mathematics

Module type: Module

Pre-requisites: None

Excluded combinations: None

Co-requisites: None

Continuing professional development: No

Professional, statutory or regulatory body requirements: None

Part 2: Description

Overview: This module introduces students to robotics, mechatronics and artificial intelligence (AI). Students will study mechanical movement (low-level control) and aspects of AI to provide a degree of autonomy (high level control) for a robot. Students will develop an understanding of robot components and decision making algorithms in order to design virtual intelligent robots. The learning is supported with simulation tools and practical experiments.

Features: Not applicable

Educational aims: The module equips students with the knowledge and understanding of theories, principles and applications of robotic systems. It introduces activities designed to develop their competencies in innovative, critical and systems thinking.

Outline syllabus: Syllabus Outline

Introduction to robotic movement and mechatronics

Awareness of various categories of robots and their applications

Principles of robotic mechatronics; mechanical/electrical/electronic integration

Sensing and actuating technology

Basic concepts on kinematics, statics, dynamics, and control of robots.

Automation

Artificial intelligence for robotics

A brief history of artificial intelligence in robotics

Task-oriented control; concepts of planning and problem solving

Concepts of behavioural robotics

Artificial intelligence algorithms

Part 3: Teaching and learning methods

Teaching and learning methods: A combination of lectures and lab demonstrations are used to present core topics from the syllabus. Laboratory sessions are used for familiarization of simulation software, and development of solutions.

Independent learning includes hours engaged with essential reading, and laboratory based development work undertaken outside the scheduled classes. Students will be expected to maintain a logbook of the work during practical sessions.

Module Learning outcomes: On successful completion of this module students will achieve the following learning outcomes.

MO1 Calculate and validate mechatronic principles for robotics [SM3b] {US1m, US3m}

MO2 Model robotic movement through the use of appropriate mathematical techniques [SM1b, EA2] {US1, E4}

MO3 Design artificial intelligence solutions to given simulated robotics problems [D2, D4] {D1i, D4}) [G1] {P1i, P1}

MO4 Maintain and write a record of experimental notes that are commensurate with industrial practice [P3, P7] {P2 and P7}

Hours to be allocated: 300

Contact hours:

Independent study/self-guided study = 228 hours

Face-to-face learning = 72 hours

Total = 300

Reading list: The reading list for this module can be accessed at readinglists.uwe.ac.uk via the following link

<https://ri.talis.com/3/uwe/lists/72F1D9CC-5C56-5924-5BD8-ADF149783B7F.html>

Part 4: Assessment

Assessment strategy: Assessment of this module consists of three tasks:

Task A will be an examination that assesses the student's understanding of analytical techniques applied to robotic systems.

Task B will be a coursework assessment for Semester 1 which consists of multiple

laboratory assignments that are carried out during the semester. This is used to assess competency in the technical aspects taught during the semester. The coursework assessment regime here has been devised to provide regular feedback and feed forward to assist students' progression in fundamental robotics principles and to prepare them for the examination.

Task C will be a group project report (2500 words) in Semester 2.

Resit Strategy:

The resit assessment will have the same structure as the first sit, i.e., three tasks as described above.

The groupwork project report will be based on the number of students resitting. If only one student is resitting, the groupwork will be scaled accordingly.

Assessment tasks:

Report (First Sit)

Description: A group project report (2500 words).

Weighting: 35 %

Final assessment: Yes

Group work: Yes

Learning outcomes tested: MO2, MO3

Examination (Online) (First Sit)

Description: Online Written Examination (2 hours + 2 hours for submission)

Weighting: 50 %

Final assessment: No

Group work: No

Learning outcomes tested: MO1, MO2, MO3

Laboratory Report (First Sit)

Description: Individual submission of a selection of laboratory reports that are submitted periodically.

Weighting: 15 %

Final assessment: No

Group work: No

Learning outcomes tested: MO1, MO3, MO4

Report (Resit)

Description: A group project report (2500 words). If there is only one student for this resit assessment, the groupwork will be scaled accordingly.

Weighting: 35 %

Final assessment: No

Group work: Yes

Learning outcomes tested: MO2, MO3

Examination (Online) (Resit)

Description: Online written Examination (2 hours + 2 hours for submission)

Weighting: 50 %

Final assessment: Yes

Group work: No

Learning outcomes tested: MO1, MO2, MO3

Laboratory Report (Resit)

Description: Individual submission of a selection of laboratory reports from Semester 1.

Weighting: 15 %

Final assessment: No

Group work: No

Learning outcomes tested: MO1, MO3, MO4

Part 5: Contributes towards

This module contributes towards the following programmes of study:

Robotics [Frenchay] BEng (Hons) 2023-24

Robotics {Foundation} [Frenchay] BEng (Hons) 2022-23

