

MODULE SPECIFICATION

| Part 1: Information | | | | | | |
|-------------------------|-------------------------------------|--|-------------------------------------|--|--|--|
| Module Title | Intelligent and Adaptive Sys | igent and Adaptive Systems | | | | |
| Module Code | UFME7K-15-M | Level | Level 7 | | | |
| For implementation from | 2018-19 | -19 | | | | |
| UWE Credit Rating | 15 | ECTS Credit Rating | 7.5 | | | |
| Faculty | Faculty of Environment & Technology | Field | Engineering, Design and Mathematics | | | |
| Department | FET Dept of Engin Design & | FET Dept of Engin Design & Mathematics | | | | |
| Contributes towards | Mechanical Engineering [Se | lechanical Engineering [Sep][FT][Frenchay][1yr] MSc 2018-19 lechanical Engineering [Sep][PT][Frenchay][2yrs] MSc 2018-19 obotics and Autonomous Systems [Sep][FT][Frenchay][1yr] PhD 2018-19 | | | | |
| Module type: | Standard | | | | | |
| Pre-requisites | None | None | | | | |
| Excluded Combinations | None | None | | | | |
| Co- requisites | None | None | | | | |
| Module Entry requireme | nts None | None | | | | |

Part 2: Description

Educational Aims: See Learning Outcomes.

Outline Syllabus: The syllabus includes:

Introduction: Review of the links with other disciplines, e.g. classical AI, psychology, robotics, ethology, neuroscience and classical control. Scope and limitations of this module, especially with respect to classical control and AI.

STUDENT AND ACADEMIC SERVICES

Learning and adaptive systems: Working definitions of intelligence, adaptive systems and learning. Adaptation through learning versus design.

Basic Architectures: Neural networks. Fuzzy systems. Evolutionary computation. Supervised, unsupervised and reinforcement learning.

Compound Architectures: Neuro-fuzzy Systems. Behaviour-based systems. Agentbased systems. Multi-agent and swarm systems.

Example applications: Review of work carried out in this Faculty, and at other establishments, in order to demonstrate the major strengths and weaknesses of the techniques.

Teaching and Learning Methods: Lectures will introduce the fundamental concepts. Tutorial sessions will be used for two purposes: they will be used to expose students to demonstrations of the basic architectures in action as well as to discuss real implementations of these new techniques. Tutorials are designed to illustrate the essential details of a particular concept or technique, and especially its strengths and weaknesses in both technical and business contexts. At all times specific examples will be used to "ground" the theory.

Contact hours will include lectures (1 hour per week) and practical tutorial sessions (2 hours per week).

Contact hours: 36 Self-study hours: 54 Coursework Preparation hours: 36 Examination Preparation hours: 24 Total hours: 150

Part 3: Assessment

The module is concerned with the study of innovative technological approaches to intelligent control and adaptive systems in robotics. The assessment strategy reflects this, encouraging independent learning and research in component B where the assignment is designed to elaborate and extend experiences gained in laboratory sessions and exercises.

The controlled conditions Component A is a written exam, , designed to assess understanding of important features in the architecture of intelligent and adaptive systems and for students to critically compare the performance characteristics of the advanced new techniques covered in this module with traditional approaches.

| First Sit Components | Final Assessment | Element weighting | Description |
|-------------------------------------|---------------------|----------------------|---------------------------------|
| Written Assignment - Component B | | 50 % | Written assignment (4000 words) |
| Examination - Component A | ~ | 50 % | Examination |
| Resit Components | Final Assessment | Element weighting | Description |
| Written Assignment - Component B | | 50 % | Written assignment (4000 words) |
| Examination - Component A | ✓ | 50 % | Examination |

| | Part 4: | Teaching and Learning Methods | | | | |
|----------------------|---|---|-----|--|--|--|
| Learning Outcomes | On successful completion of this module students will be able to: | | | | | |
| | | Module Learning Outcomes | | | | |
| | MO1 | Demonstrate a thorough understanding of the important features of intelligent and adaptive systems using both basic and compound architectures | | | | |
| | MO2 | Critically compare the performance characteristics of the advanced new techniques covered in this module with traditional approaches to selected problems in signal processing, classification and control | | | | |
| | MO3 | Apply the principles covered in this module in a practical robotics application | | | | |
| | MO4 | Study independently where necessary for the understanding of new advancements in the field | | | | |
| | MO5 | Transfer these advanced new techniques from the research sector to industrially-relevant applications | | | | |
| Contact Hours | Contact Hours | | | | | |
| | Independent Study Hours: Independent study/self-guided study | | | | | |
| | | Total Independent Study Hours: | 114 | | | |
| | Scheduled Learning and Teaching Hours: | | | | | |
| | Face-to-face learn | ing | 36 | | | |
| | Total S | cheduled Learning and Teaching Hours: | 36 | | | |
| | Hours to be allocated | | 150 | | | |
| | Allocated Hours | | 150 | | | |
| Reading List | The reading list for this module can be accessed via the following link: https://uwe.rl.talis.com/modules/ufme7k-15-m.html | | | | | |